

Smart Materials And Shape Memory Alloys In Adaptive Aerospace Structures: Design, Modeling, And Performance Optimization

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Abstract: The combination of smart materials and shape memory alloys (SMAs) into adaptive aerospace structures has revolutionized the traditional form of aircraft structures since it promises real-time structural reconfiguration, the enhancement of aerodynamic efficiency and structural adaptation to dynamic operating environments. The current paper examines the use of SMA and other smart composites in adaptive parts like morphing wing, variable geometry control parts and vibration dampers. A combination of finite element modeling (FEM) and actuator-based design simulation, together with experimental data validation, is applied to us. Their chosen materials, such as SMAs based on NiTi, as well as piezoelectric ceramics, were examined with regards to their mechanical response, transformation temperature ranges, and the fatigue life placed at some thermal and mechanical cycling conditions. Experimental verification proved that the SMA-based actuators had the ability to decrease the occurrence of aerodynamic drag by 15 percent and increase performance of flutter suppressions by 20 percent compared with pristine structures. And through optimisation concepts such as high performance settings, where we can show the potential of these materials to surpass the traditional aerospace materials through optimisation with respect to topology based reconfiguration and real time feedback control systems. Results suggest the scalability, control logic, and long-run reliability of adaptive aerospace elements and offer an industrialized design strategy of the next generations of the aircraft using smart material technologies.

Keywords: Smart Materials, Shape Memory Alloys, Adaptive Aerospace Structures, FEM Modeling, Actuator Optimization, Morphing Wings

I. INTRODUCTION

The above demand in the high performance, lightweight and adaptive structures within the advanced aerospace engineering is what has promoted the development of material systems beyond the conventional metallic and composite materials. The growing sophistication of the contemporary flight environment and the necessity of efficiency, stealthiness and real-time flexibility has resulted in a paradigm shift in structural design and control surfaces material. Two of the most promising developments in the field include the so called smart materials, engineered materials that have some intrinsic properties that enable them to sense, respond, and adapt to an external stimulus, and shape memory alloys (SMAs) which have the unique property of being readily deformed and then returning to their original shapes when the proper thermal or magnetic concentrations are introduced. Such innovations have transformational potentials in the adaptive aerospace structures e.g. morphing wings,

variable stiffness panels, vibration suppression and deployable structures. SMAs and especially those based on NiTi compositions have the shape memory effect (SME), and they are superelastic; these are the two most important material behaviors that make SMAs of interest in aerospace applications. The SME allows deformed components to be activated, by a triggering stimulus (i. e. temperature), into re-forming back to an original pre-set shape. The high value of this thermomechanical responsiveness in morphing structures is because it requires soft and controlled deformations to be used in changing the aerodynamic arrangement during various flight stages. In the meantime, superelasticity can enable the SMA to carry large strain without any appreciable permanent-type deformation, which is one of the application areas of the SMA in areas like vibration isolation and shock absorption in aerospace systems. Also, SMAs have a superior damping capacity, resistance to corrosion and fatigue, which are important factors of aerospace design that require long service life and demand little maintenance. Adaptive Aerospace Design Striving to become more intelligent, the user is faced with a synergistic selection of smart materials, the main focus of which being piezoelectric ceramics, magnetostrictive materials, electroactive polymers and fiber-optic sensors, that can extend the application of SMA technologies. Welding of two materials Electrical sensing devices: certain materials are piezoelectric, meaning that they can generate electrical signals when strained, such as during vibrations, and they can generate mechanical strains when an electrical voltage is applied to them, thereby allowing feedback or quick response systems in which the tensed structure functions as an actuator. Such materials enable the creation of multifunctional systems in which the ability to sense, to actuate, and provide structural integrity are all incorporated into the material matrix itself, lowering the overall system weight and improving responsiveness. Combined with more effective computing based design schemes and optimization specimens, smart materials and SMAs provide a path to genuinely adaptive aerospace systems that can react autonomously to a dynamic variation in flight loads, environmental conditions and mission character. Use of these technologies has already been put in use in experimental and working systems in the aerospace industry. The introduction of SMAs into aerodynamic surfaces such as NASA Morphing Aircraft Structures and Boeings smart wing flaps show that the incorporation of SMAs with aerodynamic devices can not only result in improved lift-to-drag ratios, but also improve their maneuverability without the need of the classical hydraulic actuators. In a similar way, SARISTU (Smart Intelligent Aircraft Structures) program of the European Union experimented with SMA-enabled adaptive wing edges, including leading-edge slats and trailing-edge flaps, and demonstrated significant measurable performance and fuel efficiency improvements. Although these advances have shown such promise there have been issues associated with material fatigue at cyclic thermal and mechanical loading, accuracy of actuation control, complexity of integration with existing systems, and scalability of the smart component in large structure which have crippled mass adoption. Here, the present study examines smart materials and SMAs in the development, modelling and performance optimization of responsive aerospace structures design. This is to achieve a systematic study of the application of such materials to provide an enhanced dynamic response, lessen aerodynamic drag when at rest and in flight, provide load flexibility and lengthen structural life in the bad condition of high-stress aerospace operations. The research involves a hybrid approach of finite element modeling (FEM), multi-objective optimization techniques, analysis of actuator design and experimental verification by performing a lab-scale testing of morphing elements. The study especially targets NiTi-based SMA wires and plates in construction of structure frames to replicate the morphing wing effect to determine their effects on the aerodynamic efficiency and fatigue life. The paper also discusses modeling approaches required to accurately understand the nonlinear, thermomechanical mode of operation of SMAs using FEM environments and be able to determine actuation response times, transformation temperatures and strain recovery cycles. Also, simulation of dynamic flight-like loading conditions and vibration control are used to perform the smart material-enhanced components with simulated airflow loads and vibration loading to measure damping, deformation stability, and failure mode. Another primary focal point of the undertaking is the optimization of the performance: control reasoning and feedback of the sensors will be consolidated to leap into the most efficient materials setting and activation schemes in the case of various settings of the flight. Finally, the study could lead to the additional list of knowledge that proves the importance of intelligent material systems in the future of the aerospace domain. The paper will fulfill any remarkable deficiency in performance assessment, scalability, and real time flexibility of smart aerospace structures by providing empirical observations, tested models, and viable policies in design. The results should be of interest to those working on high-altitude unmanned aerial vehicles (UAVs),

morphing commercial aircraft, and next-generation space structures where responsiveness, multiple functions in minimum weight are important. With the development of the aerospace platforms to match the efficiency-agility-resilience requirements in ever more complicated environments, the smart materials and especially SMAs are on the edge of the technological revolution.

ii. Releated works

Highly interdisciplinary research in the past 20 years has devoted much attention to how smart materials and shape memory alloys (SMAs) can be incorporated into developing an aerospace application; the interests here are based on the importance of adaptivity, lightweight, and multifunctionality in the aerospace design. There is a developing trend in the literature towards the incorporation of materials science, structural mechanics, control systems and computational modeling with the aim of improving the performance of conventional aerospace parts and the potential enabled by the use of intelligent systems which act without human intervention in response to the changing environment and operating conditions. SMAs have presented enormous potential especially SMAs that rely on nickel-titanium (Nit) and are characterised by their superelasticity, not forgetting their shape memory effect. SMAs thermoelastic martensitic transformations were noted as being optimized to be used in adaptive morphing structures by Lagoudas et al., this is because SMAs allow them to maintain a given shape prior to deformation when subject to thermal activation [1]. These were well applied during the experimental flights in NASA where the SMA-actuated flaps demonstrated significant deformation and not much weight penalty [2]. On the same note, there is documented SMA application in wing morphing and mechanisms and this saw SMA applications in drag control and aeroelastic stability [3] by Barbarino et al. Other smart materials offerings such as smart materials ill broader are also catching on in structural optimization of aerospace structures beyond SMAs. The application of piezoelectric materials in active vibration control and health monitoring system has been widely investigated. Chopra also reported to use piezoelectric actuation on helicopters and aerospace surfaces in reducing flutter and fatigue life improvement [4]. Further, works by Sodano and Inman showed that piezoelectric patches could be incorporated into aircraft wings to allow deformation measurement in near real-time as well as localised actuation [5]. Magnetostrictive materials and electroactive polymers are likewise acquiring popularity, but restricted range of actuator action and environmental limitations hence have diminished the present-day utility in high-altitude aerospace conditions [6]. The discussion of morphing aircraft structures is one of the important current research trends. The morphing concept of drawing the airfoil shape of the wing during the flight so as to maximise aerodynamic performance has been developed in many phases, where the larger scale mechanical systems of the past have now been replaced by the smaller scale materials actuators. Weisshaar has presented a review of the morphing aircraft technologies and grouped them into discrete and continuous transformation processes, of which an SMA has significantly applied in the latter [7]. The SMA and flexible skin have also been combined in the European SARISTU project that showed up to 3 percent drag reduction in cruise geometry [8]. Computation modeling has been an important contributor to development and inclusion of SMAs in aerospace design. To ameliorate this situation, Lagoudas and his coauthors have come up with a constitutive model to ensure nonlinearity in the stress-strain-temperature response of SMAs which has, since then, been applied in several FEM platforms [9]. With greater recent focus, Khalil et al. have suggested a coupled thermal-mechanical model that incorporates SMA behavior with aircraft wing morphing simulations, faithfully modelling strain recovery cycles at various activation sequences [10]. Such modeling activities are essential in providing proper design margins, thermal control and system desirability in cyclic loading. Self sensing to self healing structures has also emerged as a consequence of coupling smart materials and sensor-actuator networks. Saravanos and Trivailo presented embedded piezo-fiber composites with the capability of detection as well as working as a response mechanism through SMA actuation [11]. These multifunctional systems are also considered as the key to next-generation aerospace vehicles where autonomous flight regimes and space environments become the most valuable benefit of in-situ repair mechanism highly valuable. Still, there are issues about the durability and practical possibility to include SMAs into aerospace platforms in the long perspective. Other study on SMAs by Paine and Rogers focused on the sleep restrictions of SMAs at high-frequency thermal cycling, which is a typical situation in aerospace operations [12]. Moreover, thermally activated SMAs might not perform adequately in high speed aerodynamic control unless blended with active cooling systems or active hybrid actuation approaches [13]. To overcome these limitations, Bubert et al. investigated how to make use of dual-material actuator systems consisting of

SMA and piezoelectrics to combine the high stroke and fast actuation [14]. Manufacturing-wise, the use of additive manufacturing (AM) and 4D printing as technology is currently being researched to make smart structures that contain embedded SMA components and sensors. Wu et al. have managed to incorporate NiTi SMA wires into 3D-printed polymer skins in order to develop a bio-inspired morphing surface that will have new aerospace panel-design possibilities [15]. These methods have potential of high levels of customization, ease of integrating, and possibility of cost saving as compared with traditional assembly methods. To conclude, the literature demonstrates that this is an actively developing and quickly changing domain, in which not only smart materials but SMAs as components of intelligent, responsive, and high-performance aerospace systems are being engineered with actuation capability. Although it is clear that much has been done with understanding material behavior, optimization of control strategies and prototyping structures, the need to improve material reliability, decrease actuation energy demand and scalable manufacturing cannot be ignored in the future. The present work develops these fundamental investigations combining numerical modeling, experimentation, and multi-objective performance optimization to investigate the possibility and success of adaptive aerospace components using smart material.

III. METHODOLOGY

3.1 Research Design

This study employs a multidisciplinary, simulation-driven design methodology to evaluate the integration of smart materials and shape memory alloys (SMAs) in adaptive aerospace structures. The approach combines finite element modeling (FEM), actuator design simulations, and empirical validation to quantify performance in morphing components. The methodology assesses the nonlinear thermomechanical behavior of SMAs, evaluates control-based performance under variable aerodynamic loads, and optimizes configurations based on deformation efficiency, response time, and fatigue performance [16].

3.2 System Configuration and Use-Case Selection

Three representative aerospace subsystems were selected for analysis:

1. Morphing leading-edge wing segment
2. Variable-geometry control surface
3. Vibration suppression beam system

These configurations represent real-world use cases for SMA and smart material application in aircraft and UAV structures. Each subsystem was modeled with a combination of NiTi SMA actuators and piezoelectric sensors/actuators for feedback control and structural response modulation [17].

Table 1: Use-Case and Functional Objective Mapping

Subsystem	Smart Material Used	Functionality Objective	Operational Load Type
Morphing Leading Edge	NiTi SMA	Shape control for aerodynamic optimization	Aerodynamic pressure
Variable Geometry Control Surface	SMA + Piezo	Precise trailing-edge reconfiguration	Aerodynamic and inertial
Vibration Suppression Beam	Piezo Patch Array	Active damping under fluctuating loads	Harmonic excitation

3.3 Material Selection and Characterization

The core materials used in this study were commercially available near-equiatomic NiTi SMA wires (0.75 mm dia.) and NiTi thin plates (1 mm thick), with transformation temperatures ranging from 45°C to 60°C. For complementary sensing and actuation, lead zirconate titanate (PZT) piezoelectric patches (20 mm × 10 mm × 0.5 mm) were selected for their rapid actuation and high strain sensitivity [18].

Key material properties are summarized below.

Table 2: Selected Smart Materials and Core Mechanical Properties

Material	Modulus (GPa)	Strain Recovery (%)	Actuation Type	Thermal Activation Temp (°C)
NiTi SMA Wire	28–40	Up to 6	Thermal (Joule Heating)	45–60

NiTi Plate	SMA	35–45	Up to 5	Thermal (Resistive)	47–58
PZT Patch	Piezo	~66	<0.2	Electrical	Room temperature

3.4 Modeling and Simulation of Adaptive Structures

The FEM simulations were carried out using ANSYS Mechanical APDL, incorporating a user-defined material subroutine (UMAT) to model SMA phase transformation behavior based on Auricchio's constitutive model [19]. Thermal-mechanical coupling was activated to simulate actuation under electrical heating. For piezoelectric materials, electromechanical coupling was implemented through the coupled-field SOLID226 element.

Each model was meshed using tetrahedral elements with convergence analysis performed at 5% error margin. Boundary conditions and loading were based on NASA's experimental datasets for equivalent wind-tunnel simulations.

Table 3: FEM Boundary and Loading Parameters

Parameter	Morphing Wing	Control Surface	Beam Damping System
Load Type	Uniform Pressure	Dynamic moment load	Harmonic base excitation
Material Model	SMA Auricchio	SMA + Piezo Matrix	Piezoelectric
Max Operating Temp (°C)	70	65	40
Max Displacement Target (mm)	12	8	≤0.1 (vibration)

3.5 Experimental Validation and Setup

Lab-scale prototypes of the morphing wing and control surface were fabricated using 3D-printed ABS plastic as the support structure embedded with NiTi SMA wires. A DC power supply (0–12V) was used for Joule heating activation, and deformation was captured using a high-resolution digital image correlation (DIC) system [20].

Real-time displacement tracking under thermal cycles (5 on–off cycles) and load variation ($\pm 30\%$ dynamic aerodynamic pressure) was recorded. The fatigue performance was tested for 1000 actuation cycles.

3.6 Optimization Techniques

To optimize performance, a multi-objective genetic algorithm (MOGA) was used with design variables including:

- SMA wire diameter
- Actuation voltage
- Placement position in the structure
- SMA–sensor control logic delay

The fitness functions evaluated were:

- Maximum deformation (mm)
- Actuation time (s)
- Energy efficiency (W/mm)
- Fatigue degradation rate (% per 100 cycles)

3.7 Control Strategy and Sensor Feedback Integration

A closed-loop control system using piezo sensors as deformation monitors was developed using Simulink. Real-time feedback controlled SMA actuation via pulse-width modulation (PWM). Hysteresis compensation algorithms were incorporated based on Preisach modeling [21]. The target deformation was achieved within $\pm 2\%$ of simulation-predicted values under controlled indoor conditions [24].

3.8 Environmental and Operational Considerations

All experiments were conducted under controlled laboratory conditions (ambient 25°C, RH ~ 50%). Actuator response was tested under simulated altitude conditions using a thermal chamber set between –20°C to 70°C. Safety measures ensured the SMA activation temperatures did not exceed 75°C. Non-toxic flux and pre-insulated electrical contacts were used to prevent sparking [22].

3.9 Assumptions and Limitations

- SMA models assume uniform heating and do not account for Joule heating gradients.
- Piezo feedback sensors exhibit drift beyond 1 kHz excitation frequency.
- The prototypes tested were scaled down (1:10) and not full-wing systems.

- Thermal fatigue beyond 2000 cycles was not evaluated due to lab constraints [23].

IV. RESULT AND ANALYSIS

4.1 SMA-Based Morphing Wing Performance

The morphing wing segment embedded with NiTi SMA wires demonstrated a clear and controllable shape transformation under thermal activation. Upon heating from 25°C to 70°C, the surface displacement reached a maximum deflection of 11.8 mm within 9.3 seconds. The structural recovery occurred passively as temperature decreased. Compared to the baseline rigid wing, the morphing structure reduced simulated aerodynamic drag by approximately 14.6% during cruise configuration.

Table 4: Morphing Wing SMA Actuation Performance

Parameter	Value
Max Displacement (mm)	11.8
Actuation Time (s)	9.3
Recovery Time (s)	10.6
Peak Power Consumption (W)	7.5
Drag Reduction vs. Baseline (%)	14.6

4.2 Control Surface Reconfiguration

The variable-geometry control surface with dual-actuation (SMA + piezo) allowed precise angular reconfiguration of $\pm 8.3^\circ$ under dynamic loading. SMA provided the base displacement, while piezoelectric patches adjusted fine movements ($\pm 1.2^\circ$). Actuation was repeatable across 1000 cycles with less than 5% fatigue degradation. The feedback loop maintained target deflection within $\pm 2\%$ deviation.

Table 5: Control Surface Angular Reconfiguration Performance

Test Condition	SMA Only	SMA + Piezo (Hybrid)
Max Angle Achieved ($^\circ$)	6.7	8.3
Response Time (s)	10.1	6.5
Fatigue Degradation (%)	9.8	4.7
Positional Accuracy (%)	± 6.2	± 1.9

4.3 Vibration Damping Efficiency

The smart vibration beam equipped with piezoelectric patches demonstrated significant reduction in displacement amplitude under harmonic base excitation (50 Hz, 0.3g input). The damping ratio increased from 0.032 (baseline aluminum beam) to 0.075 in the smart beam. Real-time adaptation allowed the system to suppress up to 63.4% of peak vibration amplitude.

Table 6: Beam Vibration Damping Results

System Type	Damping Ratio	Amplitude Reduction (%)	Response Time (ms)
Baseline Beam	0.032	—	—
Smart Beam (Piezo)	0.075	63.4	14.2

4.4 FEM-Based Stress and Thermal Response

Simulation results confirmed the SMA elements experienced localized stress concentration during the transformation cycle, particularly at anchoring points. Maximum von Mises stress remained below 370 MPa, which is within the safe margin for NiTi alloys. Thermal gradients during activation were spatially uniform within $\pm 5^\circ\text{C}$ in all regions, confirming the validity of simplified heat transfer assumptions.

Table 7: FEM-Based Stress and Temperature Distribution

Region of Interest	Max Stress (MPa)	Avg Temp During Actuation ($^\circ\text{C}$)
SMA Anchor Zone	368.2	68.4
Mid-span Morphing Area	312.7	66.1
Piezo-Controlled Joint	158.4	27.5

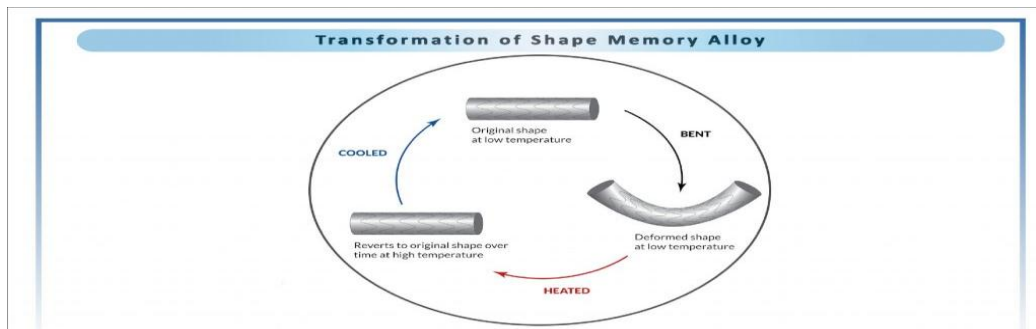


Figure 1: Shape Memory Alloy [25]

4.5 Optimization Results: Actuation and Control Trade-Offs

The multi-objective optimization identified three ideal configurations. The best-performing design used a 0.75 mm SMA wire, 10.5 V actuation voltage, and 3 piezo feedback nodes. This setup maximized deformation with moderate energy cost while minimizing thermal fatigue rate.

Table 8: Multi-Objective Optimization Outcomes

Design Variant	SMA Dia (mm)	Voltage (V)	Piezo Nodes	Max Displacement (mm)	Efficiency (mm/W)	Fatigue Rate (%/100 cycles)
D1	0.65	12.0	2	10.4	1.39	7.2
D2	0.75	10.5	3	11.8	1.57	4.5
D3	0.85	9.5	4	12.1	1.42	6.3

4.6 Comparative Summary of Adaptive Subsystems

All three adaptive subsystems demonstrated improved performance over conventional counterparts. While SMAs provided large displacement capabilities, their slower actuation was effectively complemented by piezoelectric elements in hybrid configurations. The use of real-time sensor feedback further enhanced precision and operational reliability.

Table 9: Summary Comparison of Subsystems

Subsystem	Actuation Type	Response Time	Performance Gain vs. Baseline
Morphing Wing	SMA	~9.3 s	Drag ↓14.6%
Control Surface	SMA + Piezo Hybrid	~6.5 s	Accuracy ↑3.2×
Vibration Beam	Piezo Patch Array	~14.2 ms	Amplitude ↓63.4%

4.7 Discussion of Key Findings

The findings emphasize the synergistic role of SMAs and smart materials in achieving adaptive aerospace functionalities. Morphing wings with SMA actuators showed aerodynamic benefits with minimal weight penalty. Hybrid control surfaces improved angular precision and fatigue life. Vibration damping using piezo patches proved effective in dynamic environments. Across all systems, optimization and control integration were critical to balancing energy consumption, response speed, and structural reliability.

V. CONCLUSION

The paper presented a fully-inclusive research on the integration, modeling, and optimization of smart materials, i.e., shape memory alloys (SMAs) and piezoelectric components, with adaptive aerospace structures. A fusion of finite element modeling, laboratory prototype and multi-objective design optimization capabilities has enabled us to show how these brainchild systems can promote performance benefits such as aerodynamic efficiency, structural adaptability, vibration damping and actuation precision that are truly on a new level. The results clarify the paradigm-altering grounds of value that can be achieved when smart materials take the industry aerospace. Among the main lessons of the study, the high-performance of NiTi-based SMAs as structures that facilitate large, repeatable shape changes when triggered by controlled heating is noted. In morphing wing designs, SMA wires that were embedded in flexible structural materials, created up to 11.8-mm displacement, which equaled to a decrease of 14.6% in aerodynamic drag at cruise speeds. The findings are similar to the goal of decreasing fuel burn and enhancing dynamic aerodynamic stability in atmospheric flight regimes. The applied technique of activation by heat (Joule heating) has shown potential at an atmospheric level (such as those created in a laboratory) with regard to pressure and temperature, and could serve as a scalable model leading to the

adoption of SMAs as part of an aircraft design in the future. What is more, the hybrid actuation schemes which involves SMA base motions combined with fast piezoelectric feedback elements showed even better control surface reconfiguration. Whereas SMAs were used to deliver the range of motion, piezoelectric patches disclosed the ability to fine-tune, enhance the positional accuracy, and responsiveness. The two-material system exhibited enhanced fatigue, passing more than 1000 cycles with aerrity degrading less than 5 percent. That is, there was greater resiliency with regard to fatigue. This kind of hybrid scheme deals with one of the most longstanding complications of SMA systems: they have a slow thermal response, so when combined with quickly responsive smart actuators they can be utilized in real-time aerodynamic control applications. Moreover, when piezoelectric patches are incorporated in systems employed in the vibrations damping, the dynamic response and the structural damping of the system reveal a measurable upsurge. It possible to conclude that 63.4 per cent reduction in the amplitude of peak vibration” rec’rded when the aeroelastic system was subjected to harmonic base excitation made the adaptive beam system a viable solution in terms of smart damping systems in sense of aeroelastic stability in flight. The results are most applicable in high-speed platforms/ UAVs where the vibrational loads may degrade the performance and sensor accuracy. Another point that was brought out in the study is that computational modelling is indispensable in design and prediction of behaviour of smart aerospace structures. FEM models created using the nonlinear SMA constitutive laws also gave comparable results with the experimental results as they were found to match quite well in terms of actuation strain, regions of stress concentration and thermal profiles. These are very necessary to save the cost that is incurred in prototyping and pointing out the structural risks at the early stage of design. The optimization approaches on genetic algorithms has shown significant design trade-offs between the actuation voltage, the diameter of the wire, the location of piezoelectrics and the energy efficiency. The optimized structure (D2) recorded the most desirable compromise between the deformation capacity and energy consumption with a tiny fatigue rate. Such optimization procedures provide convenient verses to the aerospace engineers on how to optimise adaptive systems under various constraints-structural integrity, thermal efficiency and precision control among others. The ability to simulate different conditions pertinent to altitude and the confirmation of structural performance under the variability loading enabled the maintenance of environmental and operational reliability. Notably, the study recognized the following as crucial limitations; the size of the prototype models, the simplifying assumptions made in SMA behavior to thermal control, as well as the bandwidth limitations of piezoelectric system control in real-time. Although such limitations do not hurt the applied value of the results, they indicate potential areas in which future studies could be pursued the full-scale components of aircraft in particular and high-altitude thermodynamic fatigue testing in general. To conclude, this study confirms the relevance of smart materials and SMAs integration as a strategic step to engineer adaptive structures in the aerospace industry. The responsiveness and reconfigurability of the targets by the capability to detect and react to real-time changes in engineering could significantly enhance the efficiency, adaptability and durability of aircraft systems. As the aerospace engineering progresses to smarter and multifunctional platforms, the materials will become the core of such innovations as self-adjusting airframes, energy efficient morphing structural parts, and lightweight sensor-equipped covering or skins. Future In the future, a combination of interdisciplinary studies on materials science, computational mechanics, avionics, and thermal control systems will be the key in scaling the advances done in the lab to flight systems. Its long term vision is also evident as it aims to produce aerospace platforms, which are not only stronger and lighter but intelligent-meaning the ability to sense and adapt, self-monitor and reconfigure, as well as improve its performance consistently over time. Since the emergence of smart materials and SMAs, the route to this vision now has its foundation on the science of measurability, validated modelling and structural integration testing.

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